Lunar occultation observations and a study of cosmic size evolution of extragalactic radio sources

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A thesis submitted for the Ph.D. degree

of the University of Bombay

August 1988

Dedicated to my parents

Ram Kishan

&

Shanti Devi

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STATEMENT REQUIRED UNDER ORDINANCES 0.770 AND 0.771

1) Statement required under 0.770:

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atement required under 0.770:
The work presented in this thesis has not been submitted
ously to the University of Bombay or to any other University for
ward of Ph.D. or any previously to the University of Bombay or to any other University for the award of Ph.D. or any other Degree.

- 2) Statement required under 0.771:
	- The work described in this thesis on the cosmic size $1.$ evolution of extragalactic radio sources has been done entirely by me. The work presented in the thesis is original. The work has for the first time indicated that the luminosity size correlation among Radio Galaxies and Quasars is different and that the cosmic evolution of radio size may be different for the different radio luminosity classes.
	- that the luminosity size correlation among Kadio G
and Quasars is different and that the cosmic evolu
of radio size may be different for the different r
luminosity classes.
The lunar occultation observations and analysis o \mathcal{P}_{\bullet} The lunar occultation observations and analysis of 305 extragalactic radio sources described in this thesis were done by me jointly with Prof. M.N. Joshi,
Dr. Gopal-Krishna and Dr. V.R. Venugopal. For the other data on extragalactic radio sources used in the study of their size evolution,appropriate references have been given in the text.

Ashok Kumar Singal

Certified that the above statements are true.

G. Swamp Govind Swarup (Sr. Professor)

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- Lunar occultation observations of 15 Abell clusters at 327 MHz Ashok K. Singal, Gopal-Krishna and H. Steppe Mon. Not. R. astr. Soc., 191, 581 (1980)
- (3) Ooty lunar occultation survey : list 9 Mohan N. Joshi and Ashok K. singal Mem. astr. Soc. India, 1, 49 (1980)
- (4) The exceptionally large flux variability of the quasar 1055+018 at metre wavelengths Gopal-Krishna, A. K. Singal and S. Krishnamohan Astr. Astrophys., 140, L19 (1984)
- (5) The alignment of distant radio sources Vijay K. Kapahi, Ravi Subrahmanyan and Ashok K. Singal Nature, 313, 463 (1985)
- Covariance of narrow-band noise in multiple beams of a phased-array system $\mathcal{A}^{\mathcal{A}}$

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(9) Some Corrections in the derivation of synchrotron radiation formulae

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As:rophys. J., 310, 733 (1986)

- (10) Polarization properties of radio cores in active galaxies D. J. Saikia, Ashok K. Singal, T. J. Cornwell Mon. Not. R. astr. Soc., 224, 379 (1987)
- (11) Ooty lunar occultation survey of radio sources A.K. Singal Astr. Astrophys. Suppl. Ser., 69, 91 (1987) (12) Cosmic evolution of the physical sizes of extragalactic

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Right in the early years of radio astronomy, it was realized that the population of extragalactic radio sources consists of extremely powerful sources, which should be visible even at large cosmological Right in the early years of radio astronomy, it was realized that
the population of extragalactic radio sources consists of extremely
powerful sources, which should be visible even at large cosmological
distances. It was h the Universe we may be able to decide between the various cosmological world-models and thus perhaps unravel some of the mysteries of the Cosmos. The subsequent studies have shown that the population of extragalactic radio sources evolves heavily with the cosmic epoch and that the evolution almost completely masks out any distinguishable features of the geometry among various world-models. But a study of the cosmic evolution of various properties of these radio sources may still yield valuable information on the conditions which prevailed in the Cosmos at different epochs. Physical size of the population of extragalactic radio sources is one such property. properties of these radio sources may still yield valuable information or
the conditions which prevailed in the Cosmos at different epochs. Physical
size of the population of extragalactic radio sources is one such propert been examined in the past either by making a direct comparison of the observed angular size distribution with redshift or from an analysis of the variation of angular size with flux density. Both these kind of studies been examined in the past either by making a direct comparison of the
observed angular size distribution with redshift or from an analysis of the
variation of angular size with flux density. Both these kind of studies
have population of extragalactic radio sources and the inference has been that there is an evolution in physical size in the sense that the sources had smaller physical sizes at earlier epochs. But a suitable luminosity-size population of extragalactic radio sources and the inference has been that
there is an evolution in physical size in the sense that the sources had
smaller physical sizes at earlier epochs. But a suitable luminosity-size
co observations, without invoking any size-evolution. there is an evolution in physical size in the sense that the sources had
smaller physical sizes at earlier epochs. But a suitable luminosity-size
correlation among the radio source population could also explain these
obser

In the present work we have investigated the problem of size distribution in the luminosity-redshift plane. In this way not only do we

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figure out the presence of any size evolution with redshift which may be

present in various luminosity classes, but we also come to know of the present in various luminosity classes, but we also come to know of the existence of any luminosity-size correlation at various redshifts. In fact there are indications in our study that both the size evolution and the luminosity size correlation may be different among radio galaxies and quasars, and accordingly we have studied these two optical classes separately. The main of the separately is the separately we have also come to know of the existence of any luminosity-size correlation at various redshifts. In fact there are indications in our study that both the size evo angular size, optical class and redshift for each source in our sample. We have observed a large sample of \sim 300 extragalactic radio sources with the Ooty Radio Telescope at 327 MHz, using the lunar occultation technique. In angular size, optical class and redshift for each source in our sample. We
have observed a large sample of ~ 300 extragalactic radio sources with the
Ooty Radio Telescope at 327 MHz, using the lunar occultation technique. largest angular size of the observed radio source is also possible from the Ooty Radio Telescope at 327 MHz, using the lunar occultation technique. In addition to the information on flux density, a reliable estimate of the largest angular size of the observed radio source is also possible from the few one-dimensional scans only. Moreover the arcsec accuracies of radio positions obtained from occultations, make it possible to get reliable optical identifications, allowing us to classify these sources into galaxies and quasars, and also leading to estimates of their redshifts, at least for the galaxies. positions obtained from occultations, make it possible to get reliable
optical identifications, allowing us to classify these sources into
galaxies and quasars, and also leading to estimates of their redshifts, at
least fo

In chapter 1 we describe main features of the Ooty Radio north-south direction, the pointing also needs to be more accurate in that galaxies and quasars, and also leading to estimates of their redshifts, at
least for the galaxies.
In chapter 1 we describe main features of the Ooty Radic
Telescope (ORT). As the ORT beams have a sharper response in the
n using a discrete set of RF and IF phase-shifters. In chapter 1 we discuss a procedure for eliminating some of the discontinuous steps which appear in the RF pointing of ORT in north-south, because of the discrete nature of these phase in the contract and the transmitted in that
direction. The pointing of ORT in north-south is done electronically, by
using a discrete set of RF and IF phase-shifters. In chapter 1 we discuss
a procedure for eli partly due to the ionosphere, shift the ORT beams almost off source when the observations are carried out near horizon. Actually the ORT is a

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phased array system in the north-south, and as such a horizontally
stratified plane parallel atmosphere should give rise to no refraction xiv
phased array system in the north-south, and as such a horizontally
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inclin chapter 1, we have discussed these refraction effects on the pointing of Incline of 11°.5 in north-south, added to the effects of a curved
atmosphere, make the pointing errors due to refraction appreciable. In
chapter 1, we have discussed these refraction effects on the pointing of
ORT. Recentl putting many putting many smaller and the off has an incline of 11°.5 in north-south, added to the effects of a curved at anomorphere, make the pointing errors due to refraction appreciable. In chapter 1, we have discussed chapter 1, we have discussed these refraction effects on the pointing of
ORT. Recently ORT has been converted into an aperture synthesis system by
putting many smaller antennas at some appropriate locations. While
discussi OSRT (Ooty Synthesis Radio Telescope). smaller antennas at some appropriate locations. While
the refractions effects, we have also cosidered the pointing of
Synthesis Radio Telescope).
By using different phase gradients across ORT, which is a phased
em in north

array system in north-south, a set of 12 simultaneous beams has been formed in north-south. During observations with the ORT, often a source may not be lying exactly on the maxima of any specific beam and accordingly the OSRT (Ooty Synthesis Radio Telescope).
By using different phase gradients across ORT, which is a phased
array system in north-south, a set of 12 simultaneous beams has been formed
in north-south. During observations with t such a case it is tempting to combine the simultaneous response in various beams to provide the signal to the signal to provide the signal morth-south. During observations with the ORT, often a source may not be lying exactly on the maxima of any specific beam and accordingly the signal may appea be lying exactly on the maxima of any specific beam and accordingly the signal may appear simultaneously within 2 or more neighbouring beams. In such a case it is tempting to combine the simultaneous response in various be chapter 2 we have discussed this problem and have shown analytically that the noise correlation among two neighbouring beams, formed from the same elements in a phased array system, as a function of the angle of separation of these beams is the same as the individual beam pattern. The result is the noise correlation among two neighbouring beams, formed from the same
elements in a phased array system, as a function of the angle of separation
of these beams is the same as the individual beam pattern. The result is
 the observed noise correlation among various beams of ORT as a function of erements in a phased array system, as a runction of the angle of separation
of these beams is the same as the individual beam pattern. The result is
almost independent of the way the beams are formed. Actual comparisons of beams and the correlation beams, are made. ved noise correlation among various beams of ORT as a function of
e of separation, with the beam pattern, both for the total power
the correlation beams, are made.
Some details of the lunar occultation technique, the metho

observations and the data analysis procedure are discussed in Chapter 3.

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Data analysis procedure includes the radio position determination, optical identification, angular size determination and the flux determination for xv
Data analysis procedure includes the radio position determination, optical
identification, angular size determination and the flux determination for
the whole source as well as for the individual components, whenever
mu XV
Data analysis procedure includes the radio position determination, optical
identification, angular size determination and the flux determination for
the whole source as well as for the individual components, whenever
mu tabulated radio and optical data on - 300 occultation sources observed by us with the ORT. Finding charts for 66 newly identified optical cases are also given. Additional notes and comments on some individual sources are also included in the text. The CRT. Finding charts for 66 newly identified optical cases are
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The cosmic evolution of physical size, and the luminosity-size
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The cosmic evolution of physical size and the luminosity-size
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investigations, an extensive data base covering a large range of radio flux
density, is needed. For this purpose we have supplemented our Ooty
occultation investigated in Chapter 4. It is argued that in order to make these
investigations, an extensive data base covering a large range of radio flux
density, is needed. For this purpose we have supplemented our Ooty
occultation sample are optically identified, and their redshifts are either known from spectroscopic measurements or are estimated from optical magnitudes. Radio spectral data for most of these sources is also available. Thus for all these sources we can calculate the radio luminosity and the physical size for any given world-model. By using this large sample of 669 sources we sample are optically identified, and their redshifts are either known from
spectroscopic measurements or are estimated from optical magnitudes. Radio
spectral data for most of these sources is also available. Thus for all
 luminosity-redshift bins, separately for galaxies and quasars. It appears that for radio galaxies the physical size increases with luminosity for redshifts < 0.5, where reliable data are available. Moreover it is found 1uminosity-redshift bins, separately for galaxies and quasars. It appears
that for radio galaxies the physical size increases with luminosity for
redshifts ≤ 0.5 , where reliable data are available. Moreover it is foun galaxies with luminosity 10²⁶ < P_{40B} < 10²⁷ W/Hz, where the median value of largest linear dimension drops from ~ 300 kpc for nearby sources to $-$ 100 kpc at redshifts $-$ 0.5. This drop in size can be represented by the

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size evolutionary models of type $(1+z)^{-n}$, for n = 3. The observed size
evolution can also be fairly well described by other models including c xvi
size evolutionary models of type $(1+z)^{-n}$, for $n = 3$. The observed size
evolution can also be fairly well described by other models including one
in which there is an exponential increase in the physical size of rad in which there is an exponential increase in the physical size of radio xvi
size evolutionary models of type $(1+z)^{-n}$, for $n = 3$. The observed size
evolution can also be fairly well described by other models including one
in which there is an exponential increase in the physical size of rad $(P_{\mu_0\alpha}$ > 10²⁷ W/Hz), there is little evidence for size evolution, at least upto redshift ~ 0.5 ; at higher redshifts data are lacking mainly because of the incompleteness of optical identification.

For quasars, unlike galaxies, there is no evidence of an increase in size with luminosity; in fact there is a hint of an inverse correlation between luminosity and size. Only a marginal size evolution seems to be present for different luminosity classes among quasars. The possibility of a differential size evolution for different luminosity classes among
galaxies and/or that of an intrinsic difference in the size distribution between luminosity, in fact there is a finit of an inverse correlation
between luminosity and size. Only a marginal size evolution seems to be
present for different luminosity classes among quasars. The possibility of
a di among galaxies and quasars can not be ruled out.

CHAPTER 1

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OOTY RADIO TELESCOPE

Ooty Radio Telescope (ORT) is an astronomical instrument designed primarily for the Lunar Occultation (LO) observations of radio sources. It OOTY RADIO TELESCOPE

Ooty Radio Telescope (ORT) is an astronomical instrument designed

primarily for the Lunar Occultation (LO) observations of radio sources. It

is in the shape of a parabolic cylinderical reflector wit metres along north-south, and a cross-section of 30 metres along east-west. The reflecting surface is made up of about 1100 stainless steel wires, Ooty Radio Telescope (ORT) is an astronomical instrument designed
primarily for the Lunar Occultation (LO) observations of radio sources. It
is in the shape of a parabolic cylinderical reflector with a length of 529
metres primarily for the Lunar Occultation (LO) observations of radio sources. It
is in the shape of a parabolic cylinderical reflector with a length of 529
metres along north-south, and a cross-section of 30 metres along east-we north-south focal line; these dipoles are grouped into 22 modules of 48 dipoles each. The voltage signals from each of these modules are divided into 12 parts and are then appropriately combined together to form 12 simultaneous neighbouring beams, separated by 3 sec6 arcmin in declination. Each of these beams can be operated simultaneously, in the total power mode into 12 parts and are then appropriately combined together to form 12
simultaneous neighbouring beams, separated by 3 sec arcmin in declination.
Each of these beams can be operated simultaneously, in the total power mode
w passed through a square law detector, and in the correlator mode where the combined output of 11 north modules is multiplied with the combined output of 11 south modules.

The ORT has an equatorial mount with its north-south axis made parallel to the axis of earth by laying it along a natural hill whose north-south slope is equal to the local latitude of the place. The system is made mechanically steerable in hour angle about this axis, while in parallel to the axis of earth by laying it along a natural hill whose
north-south slope is equal to the local latitude of the place. The system
is made mechanically steerable in hour angle about this axis, while in
declina an appropriate phase gradient across the ORT cylinder in the north-south is made mechanically steerable in hour angle about this axis, while
declination the set of 12 simultaneous beams can be steered by generati
an appropriate phase gradient across the ORT cylinder in the north-sou
direction. an appropriate phase gradient across the ORT cylinder in the north-south direction. The system is thus made steerable mechanically between -4^h
O7^m and $+5^h$ 20^m in hour angle and electronically from -36° to +36° i bandwidth.

The details of the mechanical structure and the receiver system have
described by Swarup et al.(1971) and Sarma et al.(1975). Kapahi et been described by Swarup et al.(1971) and Sarma et al.(1975). Kapahi et al.(1975) have described the feed system at the focal line. The mechanical phase shifters as described by Kapahi et al.(1975) have since then been Page 2
The details of the mechanical structure and the receiver system have
been described by Swarup et al. (1971) and Sarma et al. (1975). Kapahi et
al. (1975) have described the feed system at the focal line. The mechani steering in north-south is now possible with the help of diode phase shifters under computer control.

The ORT beams have a full half-power width of about 2:3 in right ascension, and of 5.6 sec δ and 3.6 sec δ arcmin in declination for the total shifters under computer control.
The ORT beams have a full half-power width of about 2:3 in right
ascension, and of 5.6 sec& and 3.6 sec& arcmin in declination for the total
power system and the correlator system respectiv the pointing has to be more accurate in north-south. In this chapter we discuss some aspects of the pointing of ORT, mainly concentrating on the The ORT beams have a full half-power width of about 2:3 in right
ascension, and of 5.6 sec6 and 3.6 sec6 arcmin in declination for the total
power system and the correlator system respectively. It is obvious that
the point scheme of declination pointing (Section 1.1) (ii) the discreteness in the discuss some aspects of the pointing of ORT, mainly concentrating on the
declination pointing. The various aspects discussed are: (i) the broad
scheme of declination pointing (Section 1.1) (ii) the discreteness in the
beam (iii) Effects of the pointing of ORT, mainly concentrating on the discuss some aspects of the pointing of ORT, mainly concentrating on the declination pointing. The various aspects discussed are: (i) the broad scheme of de has been made part of an aperture synthesis system called the Ooty beam pointing due to finite steps in the phase gradient (Section 1.2).
(iii) Effects of refraction on the pointing (Section 1.3). Recently ORT
has been made part of an aperture synthesis system called the Ooty
Synthesis Ra parabolic cylinders at suitable locations around ORT (Swarup 1984). In Section 1.3 we shall briefly discuss the refraction effects for the OSRT system also.

1.1 BROAD SCHEME OF THE POINTING OF ORT IN DECLINATION:

ORT, as far as its pointing in declination is concerned, is a phased array of 22 modules, as well as the dipoles within each module, are dipoles. All the modules, as well as the dipoles within each module, are dipoles. All the modules, as well as the dipoles within each module, are dipoles. All the modules, as well as the dipoles within each module, are spaced uniformly along the north-south direction. Because the north-south axis is made parallel to the axis of earth, the radio waves coming from the axis is made parallel to the axis of earth, the radio waves coming from the direction of 0° declination arrive simultaneously at all the array elements. But the radio waves coming from a direction δ° arrive wit elements. But the radio waves coming from a direction δ° arrive with a progressive time delay d sind/c between successive elements, d being the Page 3
axis is made parallel to the axis of earth, the radio waves coming from the
direction of 0° declination arrive simultaneously at all the array
elements. But the radio waves coming from a direction δ° arrive w difference $\phi = 2\pi d \nu \sin\delta/c$, between successive elements (fig. 1.1) at a frequency v.

In order to phase the array in direction δ , we have to compensate for the above phase difference by providing extra path lengths through cables distance between two adjacent elements. This gives rise to a phase
difference $\phi = 2\pi d$ v sing/c, between successive elements (fig. 1.1) at a
frequency v.
In order to phase the array in direction δ , we have to compens calculated above, in general, consists of n integer cycles (of 2π radians each) and a proper phase (fraction of a cycle). If we were to compensate only for the proper phase at a given frequency, then the integer cycles would leave a large residual phase for the other frequency components in calculated above, in general, consists of n integer cycles (of 2π radians
each) and a proper phase (fraction of a cycle). If we were to compensate
only for the proper phase at a given frequency, then the integer cycles
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only for the proper phase at a given frequency, then the integer cycles
would leave a large residual phase for the other frequency components in
the only for the proper phase at a given frequency, then the integer cycles
would leave a large residual phase for the other frequency components in
the band to broaden the beam excessively. For the ORT, all dipoles within
eac differences between individual modules are taken care of at the IF stage the band to broaden the beam excessively. For the ORT, all dipoles within the band to broaden the beam excessively. For the ORT, all dipoles within each module are phased towards the intended direction at RF stage itself u cable-lengths are introduced to compensate for the time delays in steps of integer cycles, thus maintaining the signal coherence among various modules. The available lengths of cables presently allow the steering to be done in the range of $\pm 36^\circ$ in declination.

1.2 DISCRETE STEPS IN THE PRIMARY-BEAM POINTING

The discrete nature of the phase-shifters employed for the RF system of ORT gives rise to discrete steps in its primary-beam pointing in the

 $\bar{\epsilon}_i$

Fig 1.1 A schematic of the declination setting system of the ORT

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Page
north-south direction. Here we discuss this effect and a procedure to
eliminate these steps. eliminate these steps.

As discussed earlier the ORT in the north-south direction consists of morth-south direction. Here we discuss this effect and a procedure to
eliminate these steps.
As discussed earlier the ORT in the north-south direction consists of
22 modules, each of 23 metres in length. Each module consis morth-south direction. Here we discuss this effect and a procedure to
eliminate these steps.
As discussed earlier the ORT in the north-south direction consists of
22 modules, each of 23 metres in length. Each module consi between successive dipoles is accordingly given by he no
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$$
d = \frac{23^{m}0}{48} = 0.4792 = 0.5219 \lambda_{RF} , \text{ where } \lambda_{RF} = 0.9182
$$

en successive dipoles is accordingly given by
 23^{m} 0

d = ------ = 0^m4792 = 0.5219 λ_{RF} , where $\lambda_{\text{RF}} = 0^{m}9182$

The pointing of ORT in north-south is done by generating are

priate phase-gradient. For this dipoles, with 24 dipoles on either side of its centre. The distance
between successive dipoles is accordingly given by
 $23\frac{m}{10}$
d = $\frac{m}{14792}$ = 0.5219 λ_{RF} , where λ_{RF} = 0.9182
The pointing of ORT in n between successive dipoles is accordingly given by
 $d = \frac{23^{m}}{48}$

The pointing of ORT in north-south is done by generating an

appropriate phase-gradient. For this, first the individual modules are

aligned towards th distribution at RF stage for the dipoles, we call it the 'primary-beam The pointing of ORT in north-south is done by generating an appropriate phase-gradient. For this, first the individual modules are aligned towards the intended direction by putting a proper phase distribution at RF stage f adjusted at IF stage. ibution at RF stage for the dipoles, we call it the 'primary-beam
ing' of ORT. The phase difference between successive modules is
ted at IF stage.
The digital phase-shifter system for primary-beam pointing of ORT
ys 4 bits

employs 4 bits for each dipole, wherein the phase distributions for individual dipoles can be changed only in discrete steps of $2\pi/2$ " = $2\pi/16$
radians. In the usual approach, one calculates the required phase pointing' of ORT. The phase difference between successive modules is
adjusted at IF stage.
The digital phase-shifter system for primary-beam pointing of ORT
employs 4 bits for each dipole, wherein the phase distributions employs 4 bits for each dipole, wherein the phase distributions for
individual dipoles can be changed only in discrete steps of $2\pi/2^* = 2\pi/16$
radians. In the usual approach, one calculates the required phase
distribut multiple of $2\pi/16$ for setting the bits. The phase distribution for dipoles on one side of the centre of a module is exactly antisymmetric to that for dipoles on the other side, hence we shall concentrate in our discussion on radians. In the usual approach, one calculates the required phase
distribution for each dipole and rounds it off to the nearest integer
multiple of $2\pi/16$ for setting the bits. The phase distribution for dipoles
on one s steps in the pointing of ORT for certain directions. For example, the phase distribution for mainly on one side of the module. Discrete the minimum discrete steps in the phase distribution put a restriction on the minimum on one side of the centre of a module is exactly antisymmetric to that for
dipoles on the other side, hence we shall concentrate in our discussion on
the phase distribution for mainly on one side of the module. Discrete
st starting on the common interaction of a proton in the contract of a formulation of dipoles on the other side, hence we shall concentrate in our discussion on the phase distribution for mainly on one side of the module. Dis phase-gradient across the module, the first LSB (least significant bit

.
 $\frac{1}{2}$ Page foorresponding to a phase value of $2\pi/16$) in the extreme dipole gets set

only at a minimum declination given by only at a minimum declination given by

ing to a phase value of
$$
2\pi/16
$$
)
minimum declination given by
 $2\pi(24-\frac{1}{2})$ 0.5219 sin $\delta_1 = \frac{2\pi}{16} \cdot \frac{1}{2}$
 $\Rightarrow \delta_1 \sim 8'.76$

Thus for all the intended settings between $-8'.76$ to $+8'.76$, there is no change in the phase distribution within the module, and the pointing is essentially towards 0° declination. The next change in pointing occurs when LSB is set also in the last but one dipole. This is when o₁ - 0'./0

the intended settings between -

ne phase distribution within

owards 0° declination. The nex

et also in the last but one dip
 $2\pi(23-\frac{1}{2})$ 0.5219 sin $\delta_2 = \frac{2\pi}{16} \cdot \frac{1}{2}$
 δ_2 - 9'.15 11 the intended
the phase di
y towards 0° dec
s set also in th
 $2\pi(23-\frac{1}{2})$ 0.52
=> δ_2 - 9'.15
step of 0'.39 (=

$$
2\pi(23-\frac{1}{2})
$$
 0.5219 sin $\delta_2 = \frac{2\pi}{16} \cdot \frac{1}{2}$
= $\delta_2 = 9 \cdot .15$

This step of 0'.39 (=9'. 15-8'.76) is quite small as compared with the first one of 8'.76, starting from 0° declination. Similarly the other next steps can be calculated. In general, successive steps between two consequtive settings will be small except near certain directions. These certain 'troublesome' directions are those for which the phase distribution is such that the adjacent dipoles differ in phase by integer multiples of $2\pi/16$. In case of even integer multiples, one will get the ideal setting with phase difference between successive dipoles exactly compensated for. But for odd integer multiples, all 24 dipoles on one side of the centre of module will have a constant phase error of +27/32 while the remaining 24 dipoles of the other side will get the ideal setting of $2\pi/16$. In case of even integer multiples, one will get the ideal setting with phase difference between successive dipoles exactly compensated for.
But for odd int in all cases of integar multiples there will be large discrete steps of size of the integer matriple, one will got the leads sooning
with phase difference between successive dipoles exactly compensated for.
But for odd integer multiples, all 24 dipoles on one side of the centre
of module will thus given by

 2π 0.5219 sin $\delta = \frac{2\pi n}{16}$, where n is an integer.

Accordingly it appears that in the usual approach, large steps in

². Page
primary-beam pointing occur around declinations, $\delta = 0^\circ$, $\pm 6^\circ \cdot 88$, $\pm 13^\circ \cdot 86$,
 $\pm 21^\circ \cdot 06$, $\pm 28^\circ \cdot 62$ etc. ±21°.06, ±28°.62 etc.

1.2.1 Optimum Direction Of Pointing

Apart from these large apparent discrete steps in pointing, in the above usual approach of Pointing
Apart from these large apparent discrete steps in pointing, in the
above usual approach for calculating phase distribution, the pointing
itself may not be very satisfactory. To see this let itself may not be very satisfactory. To see this let us calculate where
the beam is 'actually' pointing at when, for example, for the intended
the beam is 'actually' pointing at when, for example, for the intended Apart from these large apparent discrete steps in pointing, in the above usual approach for calculating phase distribution, the pointing itself may not be very satisfactory. To see this let us calculate where the beam is pointing direction of δ -9', we in the usual scheme, put $\pm 2\pi/16$ phase in the Apart from these large apparent discrete steps in pointing, in the
above usual approach for calculating phase distribution, the pointing
itself may not be very satisfactory. To see this let us calculate where
the beam is itself may not be very satisfactory. To see this let us calculate where
the beam is 'actually' pointing at when, for example, for the intended
pointing direction of δ -9', we in the usual scheme, put $\pm 2\pi/16$ phase i liself may not be very satisfactory. To see this let us calculate where
the beam is 'actually' pointing at when, for example, for the intended
pointing direction of δ -9', we in the usual scheme, put $\pm 2\pi/16$ phase i following way:

First, let us enumerate the dipoles within a module with an index i=1 to N, where N=24 in our case; as mentioned earlier we concentrate only on dipoles on one side of the module and for these we shall measure the phase difference with respect to the centre of the module. Let ϕ_i denote the First, let us enumerate the dipoles within a module with an index i=1
to N, where N=24 in our case; as mentioned earlier we concentrate only on
dipoles on one side of the module and for these we shall measure the phase
di dipoles on one side of the module and for these we shall measure the phase
difference with respect to the centre of the module. Let ϕ_i denote the
actual phase put for the ith dipole for a given setting. For a pointing
 dipoles. Now we form a quantity $S_{\phi} = \frac{\partial (\phi_i - \phi_i^*)^2}{\partial \phi_i^2}$. For the given phase distributions ϕ_i , S_p will be a function of sin δ . We define that value of δ to be the 'actual' pointing direction for which $S_{\stackrel{\frown}{n}}$ is a minimum. If we write $\phi_i^{\dagger}=\phi_o (i-1/2)$, where $\phi_o=2\pi d/\lambda \sin\delta$, then minimizing S_{ϕ} with respect to ϕ_0 , we get Now we form a quantity $S_{\phi} = \lambda(\phi)$
tions ϕ_i , S_i will be a function of
be the 'actual' pointing direction
 $\phi_i^{\dagger} = \phi_0(i-1/2)$, where $\phi_0 = 2\pi d/\lambda$ sinn
to ϕ_0 , we get
 $\frac{\partial S}{\partial \phi_0}$ = $\sum_{i=1}^N (\phi_i^{\dagger} - \phi_i)$

 \circ \sim $\,$

or

or
\n
$$
\frac{\phi_0}{2} \sum_{i=1}^{N} (2i-1)^2 = \sum_{i=1}^{N} \phi_i (2i-1)
$$
\nUsing the series
$$
\sum_{i=1}^{N} (2i-1)^2 = \frac{N(2N-1)(2N+1)}{3}
$$
\nwe get
$$
\frac{\phi_0}{6} N(2N-1)(2N+1) = \sum_{i=1}^{N} \phi_i (2i-1)
$$
\nor
\n
$$
\phi_0 = \frac{6}{N(2N-1)(2N+1)} \sum_{i=1}^{N} \phi_i (2i-1)
$$

This allows us to calculate the 'actual' direction of pointing in the least-mean-square sense for any given phase distribution ϕ_i .

From this we can readily calculate that for the intended pointing towards direction $\delta \sim 9$ '.0, when in the usual scheme only the 24th dipole has a phase of $2\pi/16$, the 'actual' pointing of the primary-beam is towards δ -2'.1, and for the intended pointing towards, say, δ -9'.2, when both the 23rd and the 24th dipoles have $2\pi/16$ phase each, the actual pointing of the From this we can readily calculate that for the intended pointing
towards direction $\delta \sim 9'.0$, when in the usual scheme only the 24th dipole
has a phase of $2\pi/16$, the 'actual' pointing of the primary-beam is towards
pointing errors in the usual scheme, but again it should be noted that these errors become significant only around the above mentioned 'troublesome' directions.

1.2.2 A Scheme To Eliminate Large Steps

We have shown above how to estimate an optimum direction of pointing

for a given phase-distribution. But our problem really is the other way, we need some simple scheme to calculate an optimum phase distribution ϕ_i , For a given phase-distribution. But our problem really is the other way,
we need some simple scheme to calculate an optimum phase distribution ϕ_i ,
for an intended direction of pointing . In case of manual operations, s schemes really may not be very practical,but if the phase-bits setting is done under computer control, we can employ the following scheme: First we computer of pointing . In case of manual operations, sues really may not be very practical, but if the phase-bits setting under computer control, we can employ the following scheme:
First we compute the actual re

schemes really may not be very practical, but if the phase-bits setting is
done under computer control, we can employ the following scheme:
First we compute the actual required phase values, ϕ_i^1 , for the
intended dire for an intended direction of pointing. In case of manual operations, su
schemes really may not be very practical, but if the phase-bits setting
done under computer control, we can employ the following scheme:
First we com schemes really may not be very practical, but if the phase-bits settim
done under computer control, we can employ the following scheme:
First we compute the actual required phase values, ϕ_1^1 , for
intended direction, First we compute the actual required phase values, ϕ_i^1 , for
intended direction, δ_0 , and then round off these values to the n
integer multiple of $2\pi/16$ to get ϕ_i in the usual way. Then we
calculate $\Delta \phi_i = \phi_i$ itself gives the 'actual' pointing towards $\delta_{\,\text{o}}$. But if $\text{E}_{_{\mathsf{A}}}$ is finite, then we can adjust the phase values $\phi_{\hat{1}}$ in such a way as to make \mathbb{E}_{ϕ} as sum
ting
ite, th
small
ction, integer multiple of $2\pi/16$ to get ϕ_1 in the usual way. Then we also
calculate $\Delta\phi_1 = \phi_1 \cdot \phi_1$, for all i and form the sum
 $E_{\phi} = \frac{\Delta(\phi_1)}{2i-1}$. If E_{ϕ} turns out to be zero, then this setting
itself gives calculated in section 1.2.1, will be as near to the intended direction δ_o , as possible with the discrete phase distributions. s δ_0 . But if E_{ϕ} is finite,
a way as to make E_{ϕ} as sma.
ues, the optimum direction
ear to the intended directio
ibutions.
= $\sum (\Delta \phi_i)(2i-1) \longrightarrow 0$, one
of the problem, in fact igno
that the procedure describ

While adjusting ϕ_i values to make E \mathbf{v} we can adjust the phase values ϕ_i in such a way as to make E_{ϕ} as small
as possible. Then for these ϕ_i values, the optimum direction, as
calculated in section 1.2.1, will be as near to the intended direction δ as possible with the discrete phase distributions.

While adjusting ϕ_i values to make $E_{\phi} = \int (\Delta \phi_i)(2i-1) \longrightarrow 0$, one

needs caution. An important aspect of the problem, in fact ignored by

Hatcher(1973), is that, while section 1.2.1, gives an optimum pointing direction for the given phase needs caution. An important aspect of the problem, in fact ignored by
Hatcher(1973), is that, while it is true that the procedure described in
section 1.2.1, gives an optimum pointing direction for the given phase
distribu meeds caution. An important aspect of the problem, in fact ignored by
Hatcher(1973), is that, while it is true that the procedure described in
section 1.2.1, gives an optimum pointing direction for the given phase
distrib $\sum(\Delta\phi_i)(2i-1) = 0$ could be satisfied for a variety of contrived phase distributions to give the same 'actual' pointing direction. For example, distribution, but it does not imply that the given phase distribution is
the optimum one for the pointing in that direction. In fact, the condition
 $\sum (\Delta \phi_i)(2i-1) = 0$ could be satisfied for a variety of contrived phase
di the optimum one for the pointing in that direction. In fact, the condition
 $\sum(\Delta\phi_i)(2i-1) = 0$ could be satisfied for a variety of contrived phase
distributions to give the same 'actual' pointing direction. For example
ven distributions to give the same 'actual' pointing direction. For example,
even for the 'actual' pointing towards $\delta = 0^{\circ}$, one could put large phase
jumps across the module but still satisfy $E_{\phi} = 0$. All such unreali $\sum (\Delta \phi_i)(2i-1) = 0$ could be satisfied for a variety of contrived phase
distributions to give the same 'actual' pointing direction. For example,
even for the 'actual' pointing towards $\delta = 0^\circ$, one could put large phase
j principal maxima of beam would still be pointing towards $\delta = O^{\circ}$. Thus while adjusting ϕ_i values, one has to act judiciously.

 $\label{eq:4} \begin{array}{ll} \texttt{Page} \\ \texttt{ting φ_i values, one has to act judiciously.} \end{array}$ We describe here a simple and efficient procedure, which meets the requirements and is quite fast in execution. above requirements and is quite fast in execution.

We put the corrections, in the form of discrete phase of value $\pm 2\pi/16$, starting from the dipole having largest absolute value of $\Delta\phi$, and then recalculate E_{μ} after this correction. If absolute value of E_{μ} - e
φ
tc bere a simple and efficient procedure, which meets
s and is quite fast in execution.

orrections, in the form of discrete phase of value ± 2

he dipole having largest absolute value of $\Delta \phi$, and

after this correctio decreases due to this correction then one goes to the next largest value of above requirements and is quite fast in execution.
We put the corrections, in the form of discrete phase of value $\pm 2\pi/16$,
starting from the dipole having largest absolute value of $\Delta\phi$, and ther
recalculate E_{ϕ} We put the corrections, in the form of discrete phase of value $\pm 2\pi/1$
tarting from the dipole having largest absolute value of $\Delta\phi$, and the
ecalculate E_{ϕ} after this correction. If absolute value of E_{ϕ}
ecr and also revokes the last made correction. 'corrected' E_{ϕ} is larger than the just previous one, one quits the loop
and also revokes the last made correction.
In this way one does not 'over correct' the individual phases and
mostly the corrections are done onl

In this way one does not 'over correct' the individual phases and minimizing the total number of corrections to be made. It should be noted that in this way no dipole could be in error from the required exact phase and also revokes the last made correction.
In this way one does not 'over correct' the individual phases and
mostly the corrections are done only for largest errors, thus also
minimizing the total number of corrections to this procedure is quite simple, of course first all the optimum phases to be put are calculated and only then the bit patterns are set in a single go. The that the smallest discrete step, i.e., $2\pi/16$. Implementation of procedure is quite simple, of course first all the optimum phases to be re calculated and only then the bit patterns are set in a single go.
In this p

dipole gets set at a declination value of 1.'05 and remains so till 3'.05, after which the LSB in the 23th dipoles also gets set and thus it goes on. In this procedure, starting from $\delta = 0^{\circ}$, the first LSB in the 24th
dipole gets set at a declination value of 1.'05 and remains so till 3'.05,
after which the LSB in the 23th dipoles also gets set and thus it goes on. pointing but also sets the phase distributions in an optimum way. which the LSB in the 23th dipoles also gets set and thus it goes on.
procedure not only gets rid of the apparant discrete steps in the
ing but also sets the phase distributions in an optimum way.
This procedure has effect

This procedure not only gets rid of the apparant discrete steps in t
pointing but also sets the phase distributions in an optimum way.
This procedure has effect mainly near the 'troublesome' direction
for other directions procedure itself.

Figs. 1.2 and 1.3 show the testing of the above procedure using ORT.

Fig 1.2 A comparison of the new and old procedure for the primary beam pointing using CRAB

11

 $\bar{\mathbf{v}}_j$

12

A strong source, unresolved with the primary-beam , was scanned in

morth south using only the RF phase shifters. The observations were made

using both the usual procedure and the proposed new procedure. The north south using only the RF phase shifters. The observations were made Page 1
A strong source, unresolved with the primary-beam , was scanned in
morth south using only the RF phase shifters. The observations were made
using both the usual procedure and the proposed new procedure. The
improvem improvement in pointing with the new procedure is very obvious from the Page 1
A strong source, unresolved with the primary-beam , was scanned in
morth south using only the RF phase shifters. The observations were made
using both the usual procedure and the proposed new procedure. The
improve each case the broad plateau (around $\delta = +21$ '.06 and $\delta = -6$ '.88 respectively) in the usual procedure gets replaced by a smooth curve in the new procedure.

1.3 REFRACTION EFFECTS ON THE POINTING OF ORT AND OSRT

Here we shall consider the refraction effects of only an average the usual procedure gets replaced by a smooth curve in the new procedure.

1.3 REFRACTION EFFECTS ON THE POINTING OF ORT AND OSRT

Here we shall consider the refraction effects of only an average

troposphere and ionospher troposphere or in the ionosphere, which in any case are highly time variable, will not be considered here.

1.3.1 Refraction Effects Of The Troposphere:

Refraction Effects Of The Troposphere:
First we shall consider a horizontally stratified parallel plane
phere. In this case, the normal bending of a wavefront, important for 1.3.1 Refraction Effects Of The Troposphere:

First we shall consider a horizontally stratified parallel plane

atmosphere. In this case, the normal bending of a wavefront, important for

a single dish observations, has no a single dish observations, has no effect for an interferometer system lying in a horizontal plane. This can be seen in the following way.

Let the source be lying at a true zenith angle z as seen from the top of the atmosphere, i.e, without the refraction effects. As the rays enter the atmosphere, due to refraction the rays will appear to come from a Let the source be lying at a true zenith angle z as seen from the top
of the atmosphere, i.e, without the refraction effects. As the rays enter
the atmosphere, due to refraction the rays will appear to come from a
zenith a angle z with respect to the horizontal plane will now be at an angle z' Let the source be lying at a true zenith angle z as seen from the top
of the atmosphere, i.e, without the refraction effects. As the rays enter
the atmosphere, due to refraction the rays will appear to come from a
zenith a

Fig 1.4 Geometry of tropospheric refraction for an interferometer system lying in a horizontal plane

Fig 1.5 Geometry of tropospheric refraction for an interferometer system, inclined to the horizontal plane

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Fage 15
apparent zenith angle z' instead of the true zenith angle z. But for an
interferometer it can be seen easily that the phase difference between A'
and B' is the same as it was between A and B ('.'AA'=BB'). This can interferometer it can be seen easily that the phase difference between A' and B' is the same as it was between A and B $(\cdot, A^{\dagger} = BB^{\dagger})$. This can be seen in another way: let ϕ be the phase difference between A and B, and ϕ' be the phase difference between A' and B'. Then the change in phase

$$
\phi' - \phi = \begin{pmatrix} 2\pi \\ -\pi \\ \lambda \end{pmatrix}
$$

= -\frac{2\pi d}{\lambda}
= -\frac{2\pi d}{\lambda}
= 0

Thus if we are going to compensate for the phase difference between A' and B' by using cables in the path of signal from B' (or A'), the length of these cables is independent of the refractive index of the atmosphere, Thus if we are going to compensate for the phase difference between A
and B' by using cables in the path of signal from B' (or A'), the length of
these cables is independent of the refractive index of the atmosphere
becaus This statement is true even if the refractive index changes with height and the bending of rays takes place continuously. We will be putting the cable because the final phase difference is the same as it was between A and B.
This statement is true even if the refractive index changes with height and
the bending of rays takes place continuously. We will be putting the cab refraction present. Thus the bending of wavefront due to refraction has no effect on the pointing of an interferometer system lying in a horizontal plane. This statement is true even if the refractive index changes with height and the bending of rays takes place continuously. We will be putting the cable lengths as if the source were at a zenith angle z and there were source does in the vertical plane passing the vertical plane passing the bending of rays takes place continuously. We will be putting the cable lengths as if the source were at a zenith angle z and there were no refraction refraction present. Thus the bending of wavefront due to refraction has no
effect on the pointing of an interferometer system lying in a horizontal
plane. It should be noted that the above statement is true even if the
sou position of the source, the above statement will still hold true. Let us consider now the case when our interferometer system is not
in a horizontal plane but is inclined at an angle θ with respect to
in a horizontal plane but is inclined at an angle θ with respect to

lying in a horizontal plane but is inclined at an angle 8 with respect to position of the source, the above statement will still hold true.
Let us consider now the case when our interferometer system is not
lying in a horizontal plane but is inclined at an angle θ with respect to
it (see fig. reaching A', would have travelled an extra path

 μ B'B"-AL = μ B'M sec z' - AB sin z

 $= \mu$ d sin θ sec z' - A'B" sin z $= \mu$ d sin θ sec z' - (d cos θ +d sin θ tan z') sin z

= μ d sin θ sec z' - A'B" sin z

= μ d sin θ sec z' - (d cos θ +d sin θ tan z') sin z

Now without accounting for the refraction we would have also put

-lengths in path of B' corresponding to a path differ cable-lengths in path of B' corresponding to a path difference of d $sin(z-\theta)$. Thus, we get a total path difference of

 μ d sin θ sec z' - d(cos θ + sin θ tan z') sin z + d sin (z- θ) $=$ µd sin θ sec z^{*} - d sin θ (tan z^{*} sin z + cos z) and using the fact that sin $z = \mu \sin z'$, the total path difference = d sin θ (μ cos z' - cos z). pd sin θ sec z' - d(cos θ + sin θ tan z') sin z + d sin (z- θ)
= μ d sin θ sec z' - d sin θ (tan z' sin z + cos z)
and using the fact that sin z = μ sin z',
the total path difference = d sin θ ($\$

 $2\pi d$ sin θ A

This formula for the phase difference can be interpreted in a simple and using the fact that $\sin z = \mu \sin z$,

the total path difference = d sin θ ($\mu \cos z$ - cos z).

This amounts to a phase difference = $\frac{2\pi d \sin \theta}{\lambda}$ ($\mu \cos z'$ - cos z).

This formula for the phase difference can be int This amounts to a phase difference $\frac{1}{2}$ --------- ($\frac{1}{2}$ Cos Z).
This formula for the phase difference can be interpreted in a simple
way: (i) Only the vertical component of the baseline, d sin θ , is
responsib projection of the vertical component of the baseline, d sine, along way: (i) Only the vertical component of the baseline, d sin θ , is
responsible for the refraction effects, (ii) d sin θ cos z' is the
projection of the vertical component of the baseline, d sin θ , along
zenith angl atmosphere, (iii) $2\pi d$ sine cos Z/λ is the calculated phase difference in projection of the vertical component of the baseline, d sin θ , along
zenith angle z' of the rays, arriving with a wavelength λ/μ in the
atmosphere, (iii) $2\pi d$ sin θ cos z/λ is the calculated phase difference in cables-lengths.

It can be seen easily that the above formulae is true even if the absence of refraction which we would have compensated for through
cables-lengths.
It can be seen easily that the above formulae is true even if the
source does not lie in the vertical plane passing through A'B'. Moreover
t the formula remains true even if the refractive index changes with height (of course we assume that the change in refractive index is negligible over a height difference of d sin θ). What matter here are the final values of μ (of course we assume that the change in refractive
a height difference of d sine). What matter here
and z' and the initial value of z (see fig. 1.5).

k,

The assumption of a horizontally stratified parallel plane atmosphere is quite good as long as the zenith angle of the point of observations is not very large. At large zenith angles the effect of the curvature of the atmosphere must be taken into account. For this purpose one could adopt a model of the atmosphere being in uniform concentric spherical shells around the surface of the earth, the refractive index changing as we go from one shell to another. Alternatively one could simply assume that the whole of the atmosphere is within a single homogeneous spherical shell of an appropriate scale height and with a sharp boundary. The quantities of our interest in any of these models are the final direction of arrival of the rays and the values of the refractive index at the location of the and be alternatively one could simply assume that the whole of the atmosphere is within a single homogeneous spherical shell of are appropriate scale height and with a sharp boundary. The quantities of our interest in any well as the direction of arrival do not change from one interferometer element to another.

If baseline of length d extending from element A to elemnt B is characterised by an azimuth A_b and a zenith angle Z_b , and the apparent position of the source is given by an azimuth A_{a} and a zenith angle Z_{a} , then the projection of the baseline on the direction towards the source is If baseline of
characterised by an
position of the sour
then the projection
given by (fig. 1.6)
d cos $\theta = d$ (cos Z_a

d cos θ = d (cos Z_a cos Z_b + Sin Z_a Sin Z_b cos (A_a - A_b)).

Now d cos θ is the extra path for the ray reaching element A with respect to the one reaching element B, and the corresponding phase difference is given by $\cos \theta = d \cos Z_{a}$
 $\cos \theta = d \cos Z_{a}$
 $\cos \theta = \sin \theta$
 $2\pi \mu d \cos \theta = 2\pi \mu d$
 $\lambda = 2\pi \lambda$ $Z_a \cos Z_b$ + Sin $Z_a \sin Z_b \cos (A_a - A_b)$.

e extra path for the ray reaching element A with reching element B, and the corresponding phase different
 $2\pi\mu d$
 \cdots

(cos $Z_a \cos Z_b$ + Sin $Z_a \sin Z_b \cos (A_a - A_b)$). a

cos θ is the e

he one reachist

by

cos θ 2 $\pi\mu$
 λ
 λ

If the true azis

If the true azimuth and the true zenith angle of the source are A_0 and

Fig 1.6 Geometry of the projection of the baseline on the direction towards source

Fig 1.7 Relation between $Z^{}_{\rm q}$ and $Z^{}_{\rm O}$ for a single s pherical shell mode $\scriptstyle\perp$ atmosphere

 Z_0 respecively, then without the refraction effects, the phase difference should be ecively, then without the refraction effects, the ph

e
 $2\pi d$
 $-\text{cos } Z_0 \cos Z_b + \sin Z_0 \sin Z_b \cos (A_0 - A_b)$).

based on the reasonable assumption of the spherical

$$
\frac{2\pi d}{-} \quad \text{(cos } Z_0 \text{ cos } Z_b + \sin Z_0 \text{ sin } Z_b \text{ cos } (A_0 - A_b))
$$

Now based on the reasonable assumption of the spherical symmetry of the atmosphere, the source azimuth does not change due to refraction, i.e., ${\tt A}_{\tt a}$ =A $_{\tt c}$. Thus all we have to know is ${\tt Z}_{\tt a}$ as a function of ${\tt Z}_{\tt o}$ in order to $2\pi d$
 $---$ (cos Z₀ cos Z_b + sin Z

Now based on the reasonable assu

tmosphere, the source azimuth do

. Thus all we have to know is Z

into account the refraction effe take into account the refraction effects.

There are various formulae available in literature for calculating $4a$ = A_c . Thus all we have to know is Z_a as a function of Z_o in order to
ke into account the refraction effects.
There are various formulae available in literature for calculati
as a function of Z_o depending upon the c atmosphere. For example, for a single homogeneous spherical shell model atmosphere with a uniform refractive index, $Z_{\rm a}$ and $Z_{\rm o}$ are related by There
 Z_a as a

atmosphere

atmosphere

(fig. 1.7)
 μ sin = sin (Z o - 0)

$$
\mu \sin (Z_a - \theta) = \sin (Z_o - \theta)
$$

sin Z

and

$$
\sin (Z_{\text{a}} - \theta) = \frac{\sin Z_{\text{a}}}{1 + h/R_{\text{b}}}
$$

Where h is the total assumed height of the atmosphere above the surface of earth, R_E is the radius of earth, and θ is the angle at the centre of the earth between the direction towards the observer and the point where the ray enters the atmosphere.

The other formulae, which account for the change in refractive index as a function of height, cannot be rigorously applied unless one has a precise knowledge of the relation between height and refractive index earth between the direction towards the observer and the point where the
ray enters the atmosphere.
The other formulae, which account for the change in refractive index
as a function of height, cannot be rigorously applied made to derive usable formulae. But almost all such formulae including the ones given above for the single homogeneous spherical shell model fail, many giving almost absurd results, for high zenith angles (z $> 80^{\circ}$).

In optical astronomy, Refraction-Tables since long are being used for ²
In optical astronomy, Refraction-Tables since long are being used for
large zenith angles. These tables are based on the actual observational
data and these list refraction angle, R=Z₀-Z_a, as a function of Z_a or data and these list refraction angle, $R = Z_0 - Z_{\overline{a}}$, as a function of $Z_{\overline{a}}$ or ⁴. Page 2C
In optical astronomy, Refraction-Tables since long are being used for
large zenith angles. These tables are based on the actual observational
data and these list refraction angle, $R = Z_0 - Z_a$, as a function of In operal astichant, neitherth factor radio since reng are sering associated the large zenith angles. These tables are based on the actual observational data and these list refraction angle, $R = Z_0 - Z_a$, as a function of formulae are not very satisfactory at high zenith angles. A compromise could be arrived at by the use of appropriate formulae for low zenith angles, say for $z < 80^\circ$, and using the modified optical refraction-tables for higher zenith angles. We know that for small zenith angles refraction angle, R, is directly proportional to μ -1. And we can except that even for formulae are not very satisfactory at high zenith angles. A compromise
could be arrived at by the use of appropriate formulae for low zenith
angles, say for $z \le 80^{\circ}$, and using the modified optical refraction-tables
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angle, R, is directly proportional to μ -1. And we can except that even for
large zenith angles the principal term will be proprotional to μ -1 angle, R, is directly proportional to μ -1. And we can except that even for large zenith angles the principal term will be proprotional to μ -1. In fact this will be the first order term in Taylor's series expansion o zenith angle. Zeroth order terms should obviously be zero, as there can be large zenith angles the principal term will be proprotional to μ -1. In fact this will be the first order term in Taylor's series expansion of R, in terms of μ -1; the co-effecient of this term will be highly dependen for higher zenith angles. We know that for small zenith ang
angle, R, is directly proportional to μ -1. And we can exceplarge zenith angles the principal term will be proprotional
fact this will be the first order term and use that value for high zenith angles, This procedure appears very much justified from the refraction angle (=bending) versus surface radio zenith angle. Zeroth order terms should obviously be zero, as there can be
no refraction if μ -1=0. So we could simply multiply the value of R in
refraction tables by a scaling factor given by $(\mu_{radio}^{-1})/(\mu_{optical}^{-1})$,
and gives a procedure for the computation of refraction angle as a function of p-1 at high zenith angles. In fig. 1.8 we have plotted refraction angle and use that value for high zenith angles, This procedure appears very much
justified from the refraction angle (=bending) versus surface radic
refractivity data given Crane (1976) for a zenith angle of 85°. He also
gives Also plotted are the values obtained from Table II of Crane (1976) for the corresponding value of u -1=290x10⁻⁶. The match between these two rauto coputed
les, This procedure appears very mu
except the match of refraction angle as a function
8 we have plotted refraction ang
bulated values given by Allen (1973
rom Table II of Crane (1976) for the match between t independent sets of data, one from optical and the other from radio measurements, is so well that we can say there is essentially no difference between the two of μ -1=290x10⁻⁶. The match between these two
independent sets of data, one from optical and the other from radio
measurements, is so well that we can say there is essentially no difference
between the the refraction angle-at high zenith angles.

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We use an average value of refractive index given by μ -1=250x10 $^{-6}$, for application to ORT and OSRT; error in this value is unlikely to be much greater than 10% (Mathur and Sukumar 1976). Thus to convert for our use the refractive index values from the plot, we shall use a scaling factor of 250/290-0.86. For smaller zenith angles $(z_0<80^\circ)$ we use the formula (Allen 1973), The state of $\frac{1}{2}$ ($\frac{1}{2}$ on $\frac{1}{2}$ on $\frac{1}{2}$ and $\frac{1}{2}$ on $\frac{1}{2}$ and $\frac{1}{2}$ (Mathur and Sukumar 1976). Thus to use the refractive i

(These values have already been scaled down by a factor of 0.86) R = A tan Z_0 -B tan Z_0^3 , where A=50".138, B=0".058.
(These values have already been scaled down by a factor of 0.86)
A few values obtained from this formula for $Z_0 \geq 80^\circ$ are also

plotted in fig. 1.8 for comparison purposes. It is clear that while the above formula gives a very good approximation to the observational data up to Z< 85°, for higher zenith angles, this formula cannot be used.

1.3.2 Refraction Effects Of The Ionosphere

Bending due to the ionosphere refraction as compared with that due to the tropospheric refraction is much smaller at our frequency (326.5 MHz), ionospheric refraction as compared with that
due to the tropospheric refraction is much smaller at our frequency
(326.5 MHz), ionospheric refraction being inversely proportional to
(frequency)². But it shoul (frequency)

1.3.2 Refraction Effects Of The Ionosphere

1.3.2 Refraction is more effraction as compared with that

1.926.5 MHz), ionospheric refraction being inversely proportional to

1.4.5 MHz), ionospheric refraction b to the tropospheric refraction is much smaller at our frequency

(326.5 MHz), ionospheric refraction being inversely proportional to

(frequency)². But it should be kept in mind that the ionosphere, due

to its highly ir refraction being inversely proportional to
(frequency)². But it should be kept in mind that the ionosphere, due
to its highly irregular behaviour, could produce highly variable
refraction effects during the period of con (326.5 MHz) , ionospheric refraction being inversely proportional to (frequency)². But it should be kept in mind that the ionosphere, due to its highly irregular behaviour, could produce highly variable refraction effe effects concerned with the pointing of various antennae.

Firstly, it should be noted that independent of the baseline orientation there should be no ionospheric refraction for a refraction effects during the period of continuous observations,
stretched over many hours. But here we consider only the average
effects concerned with the pointing of various antennae.
Firstly, it should be noted that in that the effects due to the horizontal gradient of electron density

 $\epsilon_{\rm g}$

are negligible (Mathur and Sukumar 1976). Then it is only the
spherical curvature of the ionosphere which produces bending of the
rays. Thus we expect no change in the azimuth angle, only the spherical curvature of the ionosphere which produces bending of the rays. Thus we expect no change in the azimuth angle, only the apparent zenith angle will be different from the true zenith angle. To calculate it we need to know the value of refraction index as a rays. Thus we expect no change in the azimuth angle, only the
apparent zenith angle will be different from the true zenith angle.
To calculate it we need to know the value of refraction index as a
function of height, which rays. Thus we expect no change in the azimuth angle, only the apparent zenith angle will be different from the true zenith angle.
To calculate it we need to know the value of refraction index as a function of height, which one can directly calculate the total bending using an expression like the one given by Hagfors (1976). The section intervals and the separation angle, only the apparent zenith angle will be different from the true zenith angle. To calculate it we need to know the value of refraction index as the plot of refraction bending vs zenith angle as given by Hagfors for \cdot an example electron density profile. We have scaled down the plot for our frequency (326.5 MHz) and also extrapolated the values below a the one given by Hagfors (1976). In absence of that we simply adopt
the plot of refraction bending vs zenith angle as given by Hagfors for
an example electron density profile. We have scaled down the plot for
our frequency be larger than a few arcsec due to the low absolute value of bending in that region.

Though the refractive index value for the ionosphere is smaller than unity, the overall effect of bending is in the same direction as due to the troposphere, i.e., the apparent zenith angle is smaller be larger than a few arcsec due to the low absolute value of bending
in that region.
Though the refractive index value for the ionosphere is smaller
than unity, the overall effect of bending is in the same direction as
due Though the refractive index value for the ionosphere is smaller
than unity, the overall effect of bending is in the same direction as
due to the troposphere, i.e., the apparent zenith angle is smaller
than the true zenith zenith angle, after the rays have entered and crossed the ionosphere, becomes the true zenith angle for the purpose of calculating the troposhperic bending. To account for the total refraction effects due to both angle, after the rays have entered and crossed the ionosphere,
becomes the true zenith angle for the purpose of calculating the
troposhperic bending. To account for the total refraction effects due
to both the iono final apparent zenith angle at the location of antennae as a function of the true zenith angle above the ionosphere.

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1.3.3 Application To ORT And OSRT

For ORT (as well as for the other smaller antennae), the east-west pointing is done purely by a mechanical rotation, thus the hour angle pointing will be directly affected by the bending due to refraction. We can calculate the apparent hour angle (H_0) of the source from its apparent zenith angle $(\frac{Z}{a})$ and the azimuth (A_0) by using the expression inting will be directly affected
We can calculate the apparent
ts apparent zenith angle (Z_a) an
ression
 $-\sin Z_a \sin A_o$
 $\cos \phi \cos Z_a - \sin \phi \sin Z_a \cos A_o$
s the latitude of ORT. Azimuth refraction. We can calculate the apparent hour angle (H_a) of the
source from its apparent zenith angle (Z_a) and the azimuth (A_o) by
using the expression
 $\begin{array}{r} -\sin Z_a \sin A_o \\ \cos \phi \cos Z_a - \sin \phi \sin Z_a \cos A_o \end{array}$
Where ϕ (=11°23')

 $\tan H_{a}$ = $\frac{-\sin Z_{a} \sin A_{a}}{200.4,000.7}$

source from its apparent zenith angle (Z_a) and the azimuth (A_o) by
using the expression
 $- \sin Z_a \sin A_0$
 $\tan H_a = \frac{1}{\cos \phi \cos Z_a - \sin \phi \sin Z_a \cos A_0}$
Where $\phi (=11^{\circ}23^{\circ})$ is the latitude of ORT. Azimuth is measured eastwards
from pointing directions, the maximum change for ORT is about 1^{m} ϕ (=11°23') is the latitude of ORT. Azimuth is measured eastwards
the north point. Fig. 1.10 shows the change in HA for different
ing directions, the maximum change for ORT is about 1^m.
ORT is a phased array system as

concerned. The apparent declination $(\delta_{\underline{a}})$ is given by

 \sin δ = sin ϕ cos χ + cos ϕ sin χ cos A $_{\rm o}$

p.

ORT is a phased array system as for as its north-south pointing is

concerned. The apparent declination (δ_a) is given by

sin δ_a = sin ϕ cos Z_a + cos ϕ sin Z_a cos A_o

The appropriate phase-gradients acros concerned. The apparent declination (δ_a) is given by

sin δ_a = sin ϕ cos Z_a + cos ϕ sin Z_a cos A_o

The appropriate phase-gradients across ORT in north-south can

calculated for the pointing towards δ_a , value of wavelength used for phase calculations should be $\lambda_{\mathtt{vacuum}}/\mu$, where μ is the refractive index value at the location of ORT. The same is true for the north-south pointing of all other individual antennae of OSRT.

West-side Story: It has been observed that when ORT is tracking a source for some continuous observations, then as the source approaches the west limit, its position shifts rapidly towards north with respect to ORT where µ is the refractive index value at the location of ORT. The same is
true for the north-south pointing of all other individual antennae of OSRT.
West-side Story: It has been observed that when ORT is tracking a source true for the north-south pointing of all other individual antennae of OSRT.
West-side Story: It has been observed that when ORT is tracking a source
for some continuous observations, then as the source approaches the west
 story, can be easily explained in terms of the refraction effects.

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Fig 1.10 Change in ORT hour angle due to refraction at different hour angles and declinations

N) *a,*

The extra phase difference between elements A and B due to refraction can be written as

The extra phase difference between elements A and B due to refra
\nthe written as
\n
$$
2\pi d
$$
\n
$$
\Delta \phi = \begin{pmatrix}\n2\pi d \\
-\pi \\
\lambda\n\end{pmatrix} \quad \text{(a) in } \delta_a - \sin \delta_0
$$
\n
$$
\frac{2\pi d}{\lambda} = \begin{pmatrix}\n\sin \phi (\mu \cos Z_a - \cos Z_0) + \cos \phi \cos A_0 (\mu \sin Z_a - \sin Z_0) \,.\n\end{pmatrix}.
$$
\nThe same expression is obtained from the equations in Section 1.3

The same expression is obtained from the equations in Section 1.3.1 by noting that $A_b=0$ and $z_b=(\pi/2)-\phi$ for ORT, here we take A as the southern element. In the above expression for $\Delta\phi$, contribution of the 2nd term, d cos ϕ cos A₀ (μ sin Z_a-sin Z₀), is very small, in fact it will be zero for a horizontally stratified parallel plane atmosphere, and thus it is finite simply due to the curvature of the atmosphere. While the first term, d sin $\phi(\mu \cos Z_{\text{a}}\text{-}\cos Z_{\text{o}})$, dominates and is due to the height difference between the north-south elements of ORT. This term is actually the same as derived in Sedion 1.3.1, but here $Z_{\hat{a}}$ also includes the effects due to the curvature of the atmosphere.

This extra phase $\Delta \phi$, if uncorrected for, will result in an apparent southwards shift in the beam-pointing with respect to the source position. Magnitude of this shift can be calculated as ame as deri

ts due to t

This extra

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or $\Delta \delta$ =

Thus the so

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2\pi d cos \delta--- \Delta \delta = \Delta \phiA
```
 μ sin δ_a - sin δ_o $\cos \delta_0$

Thus the source position will appear to shift towards north with respect to the beams; this shift will be larger at large zenith angles and it is also independent of the sign of hour-angle. Fig. 1.11 shows a plot of shift at various hour-angles and declinations. For ORT, the eastern HA

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limit is at - -4^{h} 07 $^{\mathsf{m}}$ while the west limit goes up to - +5^{h} 20 $^{\mathsf{m}}$, so the shift will be more pronounced for a source approaching the west limit. Fig. 1.12 shows some observations and the corresponding predicted shift limit is at $\sim -4^{h}07^{m}$ while the west limit goes up to $\sim -45^{h}20^{m}$, so
the shift will be more pronounced for a source approaching the west limit.
Fig. 1.12 shows some observations and the corresponding predicted s declinations, here a constant shift of 15 arcsec has been subtracted from Fig. 1.12 shows some observations and the corresponding predicted shift
for the beam position in case of a few sources chosen at different
declinations, here a constant shift of 15 arcsec has been subtracted from
the predi for the beam position in case of a few sources chosen at different
declinations, here a constant shift of 15 arcsec has been subtracted from
the predicted value from fig. 1.11. It should be kept in mind that the
observatio north-south phasing errors for ORT at the time of observations and the the predicted value from fig. 1.11. It should be kept in mind that the observations, apart from any other errors, will also be affected by any north-south phasing errors for ORT at the time of observations and the dominant declinations, here a constant shift of 15 arcsec has been subtracted from
the predicted value from fig. 1.11. It should be kept in mind that the
observations, apart from any other errors, will also be affected by any
north µ-1=250X10⁻⁶ ed value from fig. 1.11. It should be kept in mind that t
agart from any other errors, will also be affected by a
phasing errors for ORT at the time of observations and t
m (due to tropospheric refraction) in predicted val dominant term (due to tropospheric refraction) in predicted values is
directly dependent upon any variation in the assumed value of
 μ -1=250X10⁻⁶. Within these uncertainties, the agreement between
observations and the directly dependent upon any variation in the assumed value of μ -1=250X10⁻⁶. Within these uncertainties, the agreement between
observations and the predicted values is quite satisfactory. A table of
refraction bending μ -1=250X10⁻⁶. Within these uncertainties, the agreement between
observations and the predicted values is quite satisfactory. A table of
refraction bending for both the ionosphere and the troposphere has been
generate errors in declination pointing of ORT.

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The formulae of the type given in Section 1.3.1 and 1.3.2 are usuable directly in the pointing routines for the OSRT. Then we would not need to errors in declination pointing of ORT.
The formulae of the type given in Section 1.3.1 and 1.3.2 are usuable
directly in the pointing routines for the OSRT. Then we would not need to
calculate any extra differential phase elements to account for the refraction effects of average troposphere and ine formation of one opperation in section (f). Then we would not need to calculate any extra differential phase paths between various antenna
elements to account for the refraction effects of average troposphere and
ionos But one needs caution for observations near high zenith angles. The elements to account for the refraction effects of average troposphere and
ionosphere, these would be automatically taken care of by our procedure.
But one needs caution for observations near high zenith angles. The
differe arcmin at high zenith angles, thus causing a considerable distortion in the map in the form of its apparent contraction along the direction towards ionosphere, these would be automatically taken care of by our procedure.
But one needs caution for observations near high zenith angles. The
differential bending for a 2°x2° field could be of the order of a few
arcmin at h the contraction or it will restrict the hour-angle limit as a function of declination for observations of a source depending upon the width of the field of view and the maximum distortion that can be tolerated in the map.

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If the interferometer baseline becomes quite large then the differential bending for the rays reaching two elements may be appreciable. Effectively it implies that the wavef ront can no longer be considered planer on the scale of baseline lengths, but it becomes curved due to refraction within the atmosphere. Due to the fact that bending is more at larger zenith angles, the approaching wave front will be always 'concave' as seen by observers on the surface of earth (fig. 1.13). This gives rise to the first order correction to the differential phase path between elements A and B. The differential bending at two elements, with large separation, occurs because the zenith angle of a source is different due to a difference in the longitude and latitude of the two points on the surface of earth, giving rise to a differential refraction. This first order correction gets applied automatically if one uses the midpoint of the a difference in the longitude and latitude of the two points on the surface
of earth, giving rise to a differential refraction. This first order
correction gets applied automatically if one uses the midpoint of the
baselin azimuth etc. The maximum error, if this effect is uncorrected for, can be estimated in the following way:

The maximum error will occur for the sources which at large zenith angles happen to lie in the vertical plane passing through the baseline. baseline as origin for calculating the apparent zenith angle and the azimuth etc. The maximum error, if this effect is uncorrected for, can be estimated in the following way:
The maximum error will occur for the sources w differential bending due to refraction (fig. 1.13). The maximum change in true zenith angle, for a horizontal baseline, from one element to another is $\rm d/R_E^{\phantom i}$, where $\rm R_E$ is radius of earth. From figures 1.8 and 1.9, it is estimted that the maximum value of $\Delta \text{R}\cdot \text{sin}\theta \text{m}$ (1/360)d/ R_E through the basel
, where ΔR is
The maximum changed
element to ano
.8 and 1.9, it is
radians. Thus the change in differential path \leq (d²/2R_F)/360.

For a 3.5 km baseline this value is <2mm, while for a 9 km baseline it is <2 cm. Thus this change in differential path can be ignored for the OSRT baselines at 326.5 MHz.

Fig 1.13 Extra phase path between two elements of a long baseline interferometer due to differential bending of wavefront