

 Technical Report on

Broadband Analog Backend Receiver System for uGMRT

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Khodad-410504.

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ABSTRACT

The backend receiver system of the Giant Metrewave Radio Telescope (GMRT) is being upgraded and the modifications being implemented in the analog and digital sections of these receivers cater to the improved specifications of the upgraded GMRT (uGMRT).

The main specifications related to the analog section are the ability to process 30 dual polarized RF signals at the central station for a frequency range from 130 to 1600 MHz with seamless frequency coverage, and an instantaneous maximum bandwidth of 400 MHz.

This report describes the design details, implementation scheme and set-up for testing of the Receiver. It also includes the test results; lessons learned and further possible improvements in this upgrade activity.

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1. GMRT Analog Backend System (GAB SYSTEM)

1.1 Introduction:

A versatile Analog Back-end System (GAB) has been developed to process the RF signal received from antennas using high dynamic range circuits. The modifications being implemented in analog and digital backend receivers will improve the overall specifications of the Backend receiver. The major up gradation related to the analog section includes complete processing of the RF signals at the Central Electronic Building (CEB), seamless frequency coverage up to 1600 MHz and an instantaneous bandwidth of 400 MHz (max).

1.1.1 Requirement of GAB system:

As mentioned above, upgraded GMRT frequency bands i.e. seamless frequency coverage from 100 MHz up to 1600 MHz required to bring directly through optical fiber at central electronics building (CEB) for further digitization process. This OFC signal includes the desired band signal as well as other noise from rest of the frequencies. It is not feasible to directly digitize OFC output signal frequencies directly due to limitations of ADC's.

Hence higher RF frequencies are down converted in to lower frequencies and sent to ADC units. To serve this purpose as well as to adjust the input power level to ADC unit, a baseband signal converter system is designed and named as GAB system.

GAB system also provides the facility about wave shaping in different band widths. This is achieved by various types of band pass filter circuits.

GAB system provides noise injection facility at two stages, which is important for the calibration of complete receiver chain.

GAB system also provides better signal amplification, improved signal to noise ratio, improved dynamic range etc.

1.1.2 Analog backend system specifications:

- Input Freq : 30 1600 MHz
- Input Power: -24 dBm
- Max Bandwidth : 400 MHz
- Headroom : 27 dB
- Output power : -12 dBm
- Noise Contribution to FE < 0.01 K
- Filter bank 7 filter selection
- 3 BB converted signal
- Power detector at input and output
- Noise $+$ CW calibration signal at input
- Noise (var corr) calibration at ADC input.

1.1.3 List of components:

1.1.4 RF signal Chain Analysis:

For RF signal chain budget analysis, an Excel spreadsheet has developed to calculate RF parameters like Gain, Noise Figure, P1 dB, IP3, CDR, SFDR, Headroom, Noise Density, Power consumption in the system etc.

Calculations are completed for Freq. 100MHz, 1000MHz and 1500MHz.The summary of the cascade analysis is shown in Table1 below.

Table1: Cascade RF signal channel analysis

1.1.5 How GAB design completed?

First a scheme of expected GAB receiver was put considering the RF powers in various bands directly coming to Receiver room. As per scheme primary circuits/units were developed. This development was done using available components. After achieving the expected results of the same, prototype design was started.

For the prototype design, the best suited components/modules were selected. The study of parameters and comparison gave the clear ideas for the final selection of new components/modules. In the initial stage new components/modules were received as samples. Simultaneously, GAB system flow chart was analyzed using the Spectrum microwave CASCADE7.0 simulation software for RF parameter cascade study.

After cascade analysis, prototype units were designed using samples of new components/modules. With this design various tests were carried out and the results of integrated testing were compared with simulated software test results.

At this stage final design concepts were become clear to proceed for mass production. Simultaneously integrated testing results became useful to design and estimate the rack fittings, power supplies, cables etc.

Also during mass production power supplies, cable-connector assemblies to rack, mechanical rack fitting designs were completed.

After mass production of all PCB's, units were assembled in chassis and characterized individually. The same test method was carried out at PIU and integrated system level. Thus, installation for complete 30 antennas system with spares completed successfully.

1.2 Basic block diagram of GAB System:

Fig 1.2: Basic block diagram of GAB system

1.2.1 Description of signal processing flow:

The incoming RF signal is passed through a variable gain circuit whose gain can be adjusted in steps of 0.5 dB so that any variation in signal levels between antennas can be corrected at this stage and the ADC will receive same power levels. The RF signals are then passed through a RF filter bank which will have same filter as the one used immediately after the feed being used. This filter is used to improve the out of band rejection and provide a clean signal to the later stages. Since the ADC is operating at 800 MHz sampling rate, we need to down convert all signals above 400 MHz to a lower frequency. So the frequency conversion stage is provided with a bypass stage so that whenever the observation frequency is lower than 400 MHz, one can use the bypass path and the RF signal will be directly given to the ADC circuits.

For RF bands above 400 MHz a suitable LO signal is to be used to down convert the signal to 0 to 400 MHz range. The mixer unit is followed by a 400 MHz low pass filter section to attenuate the high frequency signals due to LO/RF leakage. The baseband signals thus generated are provided as two outputs, one directly as a 400 MHz signal (spare output) and the main output with a baseband filter bank which provides a facility for 100, 200, 400 MHz filter selection based on observation requirements. The power levels are adjusted for the ADC linear range.

The Local oscillator for the mixer is generated from a 10 MHz reference signal

provided by the GPS disciplined Rubidium oscillator which is the T&F standard used at the observatory. There are two ways in which the LO signal is generated. A common Signal generator which covers the full frequency range is locked to this 10 MHz reference. The output of this unit is amplified and distributed to down conversion units for all 30 antennas. This provides a facility for setting a common LO for all antennas, but provides facility to vary the set LO frequency in steps of 1 Hz. A second LO generation scheme uses individual Lo signals generated in the range 600 to 1700 MHz in 0.5 MHz steps. Here individual antennas can be set to different LO frequencies as per requirement.

The system also provides complete control & monitor of the parameters and health of the system through online and also facilities to monitor the signal levels at various stages in the receiver. A facility also exists to inject a noise or CW to the circuits to check the gain and other system parameter without removing the units from the rack

1.3 Detailed Block diagram of GAB system:

Fig1.3: Detailed Block diagram of GAB system

1.3.1 Description:

The RF signal received from antenna with an input level of -24dBm is first passed through a Mini circuits make directional coupler SYD-20-33. The coupled output is then passed through 2-way power splitter for power monitoring and detection. The direct output of SYD-20-33 then fed through 2-way absorptive RF switch M3SWA-2-50DR+ which is used to provide noise /CW injection facility.

Further, GALI-84+ is used for required RF amplification and PE4309 Peregrine make step attenuator is used to adjust power level variations with 0.5 dB step size.

Then output is fed to RF filter bank unit which includes 8 way switch HMC253QS24E .

For desired filter selection and is used for selecting the various filters i.e. 100 MHz Low Pass Filter, 130-260 MHz Band Pass Filter, 250-500 MHz Band Pass Filter, 550-900 MHz Band Pass Filter, L-Band Band Pass Filter and it also have Direct Path and a facility to connect external filter. After that using M3SWA-2-50DR+ (2-way absorptive switch) there is a provision to select direct path or mixer path for frequency conversion. The converted signal is then amplified and also noise/CW signal injection facility is provided at this stage. This switch is then followed by a 2-way power splitter, from which one of the output is taken as Spare out and another is passed through base band filter bank which incorporates 4way switch following with 100MHz, 200MHz, 400MHz LPFs. It also has a facility to connect external filter if required. Selectable output is connected to a Buffer amplifier. A coupled output is taken for Monitor purpose.

The ADL5513 IC is used as RF detector capable of accurately converting an RF input signal to a corresponding decibel-scaled output.

1.4 Ideal Response of System:

Fig1.4: Ideal response of system

1.5 Measured response of GAB system:

1.5.1 Input Spectrum of Analog Backend system:

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Fig1.5.1: Input Spectrum of Analog Backend system:

1.5.2 Output Spectrum of Analog Backend system:

2 Analog Receiver PIU

2.1Block diagram of Analog Receiver PIU:

2.2 Description:

At the first, RF signal received from antenna is passed through a variable gain amplifier (VGA) unit whose gain, can be adjusted in steps of 0.5 dB so that any variation in signal levels between antennas can be corrected at this stage. Since the ADC is operating at 800 MHz sampling rate, we need to down convert all RF signals which are above 400 MHz to a lower frequency. For down conversion, frequency conversion unit is provided with a bypass stage so that whenever the observation frequency is lower than 400 MHz, one can use the bypass path and the RF signal will be directly given to the ADC circuits. For RF bands above 400 MHz, a suitable LO signal from 600 MHz to 1700 MHz is to be used to down convert the signal from 0 to 400 MHz range. The mixer unit is followed by a 400 MHz low pass section to attenuate the high frequency signals due to LO/RF leakage. Buffer is used for drive the signal through RF Cable up to ADC input.

2.2.1 VGA unit:

The variable gain amplifier unit includes Minicircuits make directional coupler SYD-20-33+ which is wideband i.e. 30-3000 MHz, low mainline loss of 1.6 dB typ. with excellent VSWR, 1.15:1 typ. at all ports.

It has 2-way absorptive RF switch M3SWA-2-50DR+ with an operating range from DC to 4500MHz and it provides high isolation, 65dB at 1GHz with low insertion loss 0.7dB.

GALI-84+ is used for RF amplification which has operating frequency range from DC to 6 GHz and it provides High gain, 25.6 dB typ. at 100 MHz with 38dBm IP3 and 21.9P1dB.

IC PE4309 Peregrine make step attenuator is used to adjust power level variations.

This product is a high linearity, 6-bit RF Digital Step Attenuator (DSA) covering a 31.5 dB attenuation range in 0.5 dB steps. The Peregrine 50Ω RF DSA provides a parallel CMOS control interface and it operates on 3-volt to 5-volt supply. It maintains high attenuation accuracy over frequency and temperature and exhibits very low insertion loss and low power consumption. To monitor power levels at front panel, 2 way RF divider ADP-2-20 is used which has operating frequency 20 to 2000MHz with low insertion loss, 0.7 dB typ.

The ADL5513 IC is used as RF detector capable of accurately converting an RF input signal to a corresponding decibel-scaled output. The ADL5513 maintains accurate log conformance for signals between DC to 4 GHz. The input dynamic range is typically 80 dB (re: 50Ω) with error less than $\pm 3dB$.

2.2.2. CNV Unit:

As mentioned above, for the down conversion, frequency conversion (CNV) unit is provided with a bypass stage so that whenever the observation frequency is lower than 400 MHz, can be use through bypass path and the RF signal will be directly given to the ADC circuits. In the conversion path, for RF bands above 400 MHz, a suitable LO signal, from 600 MHz to 1700 MHz is to be used to down convert the signal from 0 to 400 MHz range. The conversion path and direct path is made possible by using two way RF switch M3SWA-2- 50DR+ at both ends. SYM-2500 wideband (1 to 2500 MHz) level 7 mixer module is used for frequency conversion which is having low conversion loss 6.5 dB and high L-R isolation 50 dB. The mixer circuit is followed by a 400 MHz low pass section to attenuate the high frequency signals due to LO/RF leakage. A fixed resistive attenuator of 8 dB (Pie type) is put in the direct path to compensate the conversion loss due to mixer module in the conversion path.

2.2.3. BUFFER Unit:

Buffer is used for drive the signal through RF Cable up to ADC input. The conversion unit output is given to the buffer unit as an input. Gali-6 amplifier is used for further amplification. After that noise injection facility is provided using M3SWA-2-50DR+ switch for calibration of the digital chain. Using PRSC-2050 power splitter, one output is taken as spare for future backend and another is given as an input to the BB filter PIU.

2.3 Test Results for Analog Receiver PIU:

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Fig 2.3.1: RF Input to OUT1 & OUT 2 response plot (100-400 MHz) Input@-30dBm.

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Fig2.3.2: RF Input to OUT1 & OUT 2 response plot (400-800 MHz)Input@-30dBm/LO-800MHz

Spectrum		Ref Level 20.00 dBm	Spectrum 2	(\overline{x})	\rightarrow RBW 300 kHz				罗
Att		40dB	SWT 2.5 ms \bullet VBW		3 kHz	Mode Auto FFT			
		● 1Pk View● 2Pk Max							
							M1[1]		-25.24 dBm
10 dBm-									100,000 MHz
							M2[1]		-28.06 dBm
0 dBm			M ₅		M6				200,000 MHz
-10 dBm			\mathbf{w}		$\overline{}$			M 7	
-20 dBm $-$			M1		M ₂			M3	
-30 dBm \cdot					$\overline{\mathbf{v}}$			\mathbf{v}	
-40 dBm									
-50 dBm									
-60 dBm									
-70 dBm-									
	Start 10.0 MHz				691 pts				Stop 400.0 MHz
Marker									
Type	Ref Trc		Stimulus		Response	Function			Function Result
M1		$\mathbf{1}$	100.0 MHz		-25.24 dBm				
M ₂		$\mathbf{1}$	200.0 MHz		-28.06 dBm				
M ₃		$\mathbf{1}$	300.0 MHz		-27.50 dBm				
M ₄		$\mathbf{1}$	400.0 MHz		-36.06 dBm				
M ₅		\overline{c}	100.0 MHz		-6.81 dBm				
M ₆		$\mathbf{2}$	200.0 MHz		-10.15 dBm				
M7		2	300.0 MHz		-9.72 dBm				
M ₈		\mathbf{Z}	400.0 MHz		-19.46 dBm				

Fig2.3.3: RF Input to OUT1 & OUT 2 response plot (800 -1200MHz) Input@-30dBm/LO-800MHz

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Fig2.3.4: RF Input to OUT1 & OUT 2 response plot (1200 -1600MHz) Input@- 30dBm/LO-1200MHz

3.0 LO SYNTHESIZER PIU:

3.1: Block diagram of LO Synthesizer PIU:

Fig3.1: Block diagram of Lo synthesizer PIU

3.2 Description:

The LO signal for the mixer unit uses 105MHz reference signal .This 105MHz reference signal provided is taken through LO master system at receiver room. There are two schemes for LO signal generation.

A common Signal generator which covers the full frequency range is locked to the 105 MHz reference signal. The output of the signal generator is then amplified and distributed to down conversion units for all 30 antennas.

This scheme provides a facility for setting a common LO frequency for all antennas with the steps of 1 Hz. A second LO generation scheme uses individual LO signals generated in the range of 600 to 1700 MHz in 0.5 MHz steps. With this scheme individual antennas can be set to different LO frequencies as per requirement.

3.3: Test results for LO Synthesizer PIU:

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Fig3.3.4: Isolation between CW & FSW with CW Path ON

4.0 REF. Distribution PIU

4.1 Block Diagram

Fig4.1: Block diagram of Reference Distribution PIU

4.2 Description:

The LO reference of 105Mhz is taken from the Freq. & Time Standard (FTS) system amplified using a power amplifier from Minicircuits lab and then distributed to backend system for each antenna using pulsar microwave make 4 way splitter network. The power levels are adjusted using attenuators/amplifiers at every stage.

The circuit has facility to select among 105 MHz signal from one of the two available FTS units. The output reference signal is provided at +3dBm to the LO synth unit. In the LO synth unit, a 2 way switch is used to select the common signal source or the FSW unit as per requirement.

The signal is then amplified and split to two signal for each pol channel in an antenna. A directional coupler with power detector circuits is used for monitoring the signal levels regularly. A high performance signal source i.e. Agilent make N5161A is used as the common LO source for reference distribution as per scheme.

5. RF Filter bank PIU

5.1 Block Diagram:

Fig5.1: RF Filter bank PIU

5.2 Description:

RF filter unit is part of a GMRT Analog Backend System and is used for selecting the various filters i.e. 100 MHz Low Pass Filter, 130-260 MHz Band Pass Filter, 250-500 MHz Band Pass Filter, 550-900 MHz Band Pass Filter, L-Band Band Pass Filter and it is also have Direct Path and a facility to connect external filter. The HMC253QS24E are low-cost non-reflective SP8T switches in 24-lead QSOP packages is used in 8 Way RF switch unit featuring wideband operation from DC to 2.5 GHz. The switch offers a single positive bias and true TTL/CMOS compatibility. A 3:8decoder is integrated on the switch requiring only 3 control lines and a positive bias to select each path.

5.3Test results for RF FILTER PIU

Fig5.3.2: 100 MHz Low Pass Filter

Fig5.3.3: 130MHz to 260 MHz BandPass Filter

Fig 5.3.4: 250MHz – 500MHz BandPass Filter

 Fig 5.3.6: L-Band Band Pass Filter

6. Base band filter bank PIU

6.1 Block Diagram

6.2 Description

The output of Analog Rx PIU is given to the Base band Filter bank unit. The main function of this unit is to provide the facility to utilize 100MHz, 200MHz and 400MHz LPF's.

This incorporates 4way switch following with 100MHz, 200MHz, 400MHz LPFs. The LPF's used are passive filters and been designed using Gensys Software. It also has a facility to connect external filter if required.

Input signals are amplified and fed to Low pass filter bank through a 4 way RF Switch which is controlled through 2 control bits. Selectable output is connected to a Buffer amplifier. A coupled output is taken for Monitor purpose.

All this blocks are divided into a four different RSW, BUF, LPF, DDD& PS units. Where RSW unit consist RF Amplifier followed by a RF Switch. BUF unit consist RF switch followed by Directional Coupler & a Buffer amplifier. DDD unit consist power divider & Detector IC and DC amplifier.

6.3 Test results for BB FILTER PIU:

Fig 6.3.1: BB IN to BB OUT Frequency response @ 100MHz Low Pass Filter Selection (Input:-30dBm)

Fig 6.3.2:BB IN to BB OUT Frequency response @ 200MHz Low Pass Filter Selection

Fig6.3.3:BB IN to BB OUT Frequency response @ 400Mhz Low Pass Filter Selection

Fig6.3.4: BB IN to BB OUT Frequency response @ Direct Path selection

7.0 NOISE CAL PIU

7.1 Introduction:

Noise CAL PIU unit is used for calibration of the GAB system and GPU correlator system . This unit is sub classified in ANACAL and DIGICAL. ANACAL unit is used for calibration of analog backend chain (GAB) system and DIGICAL unit is used for calibration of Digital backend chain.

Specifications of system:

- Max Output power : -10dBm.
- 2. Digital Noise Cal : 0 to 400 MHz Max Output power : -17 dBm

1. Analog Noise Cal : Broadband Noise of 0 to 2GHz

7.2 Block Diagram of ANACAL and DIGICAL Noise PIU:

Fig7.2.1: Block Diagram of ANACAL Noise PIU

Broadband Analog Backend Receiver for uGMRT 35

 Fig7.2.2: Block Diagram of DIGICAL Noise PIU

Description:

Noise com make source NC2601 is used as Broadband noise source which is followed by power combiner to inject C.W. Signal for calibration of GAB Analog Rx PIU. After this HMC472LP4 variable attenuator is used to adjust the output power level with 0.5dB step size.

After this signal is being amplified using SBA5089Z amplifier with 20dB gain. There is a facility to monitor the power level at front panel and through online by using DDD (Directional coupler, Divider, Detector) chassis. The difference between ANACAL and DIGICAL unit is that DIGICAL has an additional 400MHz LPF included.

7.3: Test results for NOISE CAL PIU:

Spectrum								受
		Ref Level -30.00 dBm			\bullet RBW 300 kHz			
Att		0 dB	SWT $1.7 s \bullet VBW$		3 kHz		Mode Auto Sweep	
@1AP Clrw								
							M5[1]	-62.48 dBm
			M2					2.00000 GHz
					M3		M1[1]	-51.54 dBm MAZ
							1891 TT Turnway	5.00 MHz
Start 0.0 Hz					691 pts			Stop 2.0 GHz
Channel Power								
		Bandwidth 2.00 GHz			Power -11.22 dBm		Tx Total -11.22 dBm	
Marker								
Type	Ref	Trc	Stimulus		Response		Function	Function Result
M1		$\mathbf 1$	5.0 MHz		-51.54 dBm			
M2		$\mathbf{1}$	500.0 MHz		-46.63 dBm			
M3		$\mathbf{1}$	1.0 GHz		-50.44 dBm			
M4		$\mathbf{1}$	1.5 GHz		-54.82 dBm			
M ₅		$\mathbf{1}$	2.0 GHz		-62.48 dBm			
IF OVLD							Measuring	12.03.2013 \blacksquare 14:31:24

Date: 12. MAR. 2013 14:31: Fig 7.3.1: Frequency response of Analog Noise Cal

Date: 12.MAR.2013 14:29:53

Fig 7.3.2 : Frequency response of Digital Noise Cal

8. Temperature monitoring system

8.1Introduction:

In the upgraded GMRT system some systems and components are critical so it was decided to design a temperature monitoring system that could measure and record temperature at various locations in receiver room, critical components and various sub systems

Design specification of temperature monitoring is as follows:

In the temperature monitoring system we have used National semiconductor make LM35.The LM35 series are precision integrated-circuit temperature sensors, whose output voltage is linearly proportional to the Celsius (Centigrade) temperature. The LM35 thus has an advantage over linear temperature sensors calibrated in Kelvin, as the user is not required to subtract a large constant voltage from its output to obtain convenient Centi-grade scaling. The LM35's low output impedance, linear output, and precise inherent calibration make interfacing to readout or control circuitry especially easy. It can be used with single power supplies or with plus and minus power supplies. The LM35 is rated to operate over a -55 degree to +150 degree centigrade temperature range.

How to measure temperature?

Using the LM35 is easy, simply connect the pin no1 to power supply and the pin no 2 to ground pin 3 will have an analog voltage that is directly proportional (linear) to the temperature. The analog voltage is independent of the power supply.

To convert the voltage to temperature, simply use the basic formula: formula: Temp in Celsius = $(Vout in mV) / 10$

8.2 Block Diagram:

8.3 Description:

Temperature sensors are connected as an input to analog multiplexer. Maximum 8 sensors can be connected to one multiplexer unit. This multiplexer unit is connected to National instruments make hardware DAQ (data acquisition) NI USB 6008, which is having Analog and digital input and output ports. Control point for multiplexer is connected to digital output of DAQ and the output of multiplexer is connected to analog input of the DAQ.

The DAQ is controlled by national instruments make software called Lab view. The program using Lab view performs following task:

It sends digital data 0000 reads back multiplexer o/p, this will be channel1 displays on to front panel of the program then it will increment digital data 0001 and reads channel2 data and write it into file.

8.4Test Results:

Fig8.4.1 Plot using data recorded in Lab using Labview Software

 Fig8.4.2 Plot using data recorded in correlator room

9. SMPS based Power supply for GAB system

9.1 Introduction:

The GAB System installed in receiver room needs a power supply for each rack. A new SMPS based power supply instead of linear power supply is designed for GAB system which is also integrated in RFI shielded enclosure.

This unit consist Meanwell make SMPS modules of $+9V$, $+15V$, $+27 V & -9V$ with 100 watt capacity of each. We have carried test for min-max voltage level variation using the potentiometer on the module, ripple at no load and full load.

9.2 Feature of SMPS power supply:

1. 19inch Rack mount arrangement.

2. Independent module that gives you flexibility during maintenance.(easily repairable)

3. Shielded AC power line filter with fuse for AC power input at the back side.

4. Feed through with terminal strip arrangement for temperature monitoring and DC output power supply at the back side.

5. AC power fan arrangement at the bottom for cool air circulation.

6. Hot air out using hole arrangement on the top side.

7. LED monitoring at the front side.

9.3 Technical specifications Lab Measurements:-

1) It is consisting of Meanwell make SMPS modules of $+9V$, $+15V$, $+27V$ with 100 watt capacity of each. In power supply box we used modules listed below

This output voltage adjusted by independent potentiometer.

Table 9.3.1 Ripple

3) Over voltage protection:-

Recovers automatically after fault condition is removed , this is Hiccup mode.

4) Output load regulation:-

Table 9.3.2 Output load regulation:

9.4 Temperature variation on SMPS power supply :-

The overall temperature variation seen for the SMPS power supply kept inside the Receiver room is between 21°C to 27°C. The data recorded at every one minute interval on each SMPS unit for 20 days.

Fig.5:- Temperature variation seen for 20 days at the top layer of SMPS for each SMPS unit between 21°C to 27°C.

Fig9.4 Temperature variation on SMPS power supply

10 Control & Monitor UNIT:

10.1 Block Diagram

Fig10.1 Block diagram of Control & Monitor PIU

10.2 Description:

GAB control and monitoring does controlling of Analog Receiver system, Baseband Filter, RF filter and Local Oscillator system. To control these systems it use MCM card. MCM card has 32 Output Lines which are used to set GAB subsystems. Out of 32 Output lines 18 lines for set Analog Receiver system channel1 and Channel2.

With these 18 lines we can set Attenuation, Input selection (Antenna input or Noise input), Mixer or Direct path. 6 lines for RF filter selection of channel1 and channel2and 4 lines for baseband filter selection of channel 1 and channel 2. 100 MHz, 200MHz, 400MHz and Direct path. 2 line for source of local oscillator i.e. external (signal generator for LO < 500 MHz) FSW. SPI bus is use to set Local Oscillator frequency.

64 input lines of MCM card are used to monitor various parameters like attenuations, selected path, Power supply and temperature.

			BASE BAND FILTER MONITORING-1	BASE BAND FILTER MONITORING-2					
FRC	$D37-I$	D ₁₅ -3	Signals	FRC	$D37-H$	D ₁₅ -3	Signals		
20	23	$\mathbf{1}$	BBF	52	23	$\mathbf{1}$	BBF	∾	
21	24	9	BBf	53	24	9	BBf		
22	25	$\overline{2}$	MON ₁	54	25	$\overline{2}$	MON1		
23	26	10	MON ₂	55	26	10	MON ₂		
24	27	3	Power	56	27	3	Power	$D-15$ TO BB filter X	
	28	15	GND		28	15	GND		
		4				4			
	LO		MONITORING-1&2						
FRC	$D37-I$	D15-4	Monitoring	FRC	$D37-H$				
25				57	29	$\mathbf{1}$	CW1		
26				58	30	9	CW ₂		
27				59	31	2	Lock Det. 1		
28				60	32	10	Lock Det. 2	TO LO PIUX	
				61	33	3	Power Mon.	D-15	
29			NC	62	34		Temp. Mon.		
30			NC		35	15	GND		
31			NC	63	36		NC		
32			NC	64	37		NC		

Table10.3.1 Table for monitoring points

Table10.3.1 Table for monitoring points

Table10.3.2 Table for control points

S – Synthesizer, **Si** – Signal generator, **A –** Antenna, **N –** Noise source, **D –** Direct, **M** – Mixer, **1 / 2** – Channel select

10.4 Snapshot of New MCM monitoring window

Fig10.4 Snapshot of monitor window

10.5 Snapshot of New MCM Control window

Fig10.5 Snapshot of monitor window

CONCLUSION

The GMRT Analog Backend (GAB) has been upgraded as a part of uGMRT, with seamless frequency coverage of 130 to 1700 MHz, and an instantaneous selectable bandwidth up to 400 MHz.

Dual polarized independent LO synthesizer system has been designed with improved Phase noise specifications to help user to perform the polarized dependent observations.

A computerized based ALC has implemented using RF Power detectors implemented in the system and computed, based on the gain requirements in terms of attenuation setting.

A Frequency and Time standard (FTS) system specifications are improved with help of new instrument i.e. PTS make GPS10RBN model.

The various sub systems are newly developed in house and implemented are such as RFI shield Ethernet Switch, RFI shield SMPS power supply which helped to optimized the overall cost.

Rack wiring and fabrication were also carried in- house under the mass production and units were characterized for the performance test at chassis as well as integrated PIU level. This design provides analog spare output which can be used independently as backend output without disturbing the working chain.

A fully functional 30 antenna GAB system has been released with online interface for control and monitors the system parameter.

Annexure

Cascaded Analysis Result: Theoretical analysis @100 MHz :

Input power : -24 dBm Signal Bandwidth : 400MHz Impedance : 50 ohm

Theoretical analysis @ 1500 MHz:

Cascaded Analysis Result:

Photographs of Final GAB System Installed at Central Electronics Building:

GAB System Rack – Front Side

GAB System Rack – Rear Side